delair.ai

PLATFORM

The leading visual intelligence platform



delair.ai

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Platform overview.

| Aggregate Easily centralize all your data from any source in one platform | | | | |
|---|---|--|--|--|
| Drone agnostic | The platform is designed to aggregate, manage and analyze data from all professional drones | | | |
| Native compatible drone data | UX11 RGB, UX11 Ag (Multispectral) | | | |
| Certified compatible drone data | DJI Phantom 4 Pro series and Mavic 2 Pro series, Quantum Systems, Wingtra One | | | |
| Compatible drone sensors data | Micasense Rededge-MX, Micasense Rededge-Mini, Micasense Rededge 3, Airinov multiSPEC 4C, Airinov PRI, Parrot Sequoia, Parrot Sequoia+, FLIR Tau 2, FLIR Vue Pro,FLIR Vue Pro R, RGB sensors | | | |
| Other compatible data inputs | RGB georeferenced data-sets from land-based and handheld devices, such as DSLR cameras or smartphones. .las Point Clouds to standards 1.2 & 1.4, obtained from airborne LiDARs or ground-based laser scanners raw data. loT sensor data | | | |

| Manage Harness the power of visual data | | | | |
|--|---|---|--|--|
| User management | Assigned permissions based on specific user needs: manager, user, operator, contributor | View permissions, Upload/download data permissions, Manipulate data permissions | | |
| Processing configuration | Set your parameters and choose the best photo- grammetry engine for your data processing | PIX4D Engine Agisoft Metashape Coordinate system: EPSG/ESRI, local coordinates GCP tagging RTK/PPK processing | | |
| Georeferencing | Advance geospatial referencing system | EPSG/ESRI coordinate system, local coordinates system | | |
| Visualize | Gain a holistic view of your sites, progress and operations across your company | Orthomosaic, Dynamic Digital Surface Model, Slope Map, Custom contours, Source images, Comparison view, Change map, 3D Mesh, 3D Point Cloud, Specific Overlays | | |
| Collaborate | Add comments to annotations and assign them to the right member of your team | Assign annotations, Notify, Review annotations | | |
| Storage | Secure and scalable storage capacity. Monitor your total data storage from the administration console: images, products, reference files | | | |
| Archiving | Secure cloud archiving , 24h SLA for data access from archive | | | |

| Develop and integrate Use delair.ai as a backend for your application, deploy custom analytics or exchange data with your information system | | | | |
|---|--|--|--|--|
| APIs | Interact with delair.ai from your platform, using the APIs from any programming language | Public APIs enable you to : access GIS data : rasters, vectors, point clouds, – launch analytics – manage projects, users – annotate data – - measure volumes and profiles – share raster tiles | | |
| SDK | Python SDK provides you with the boiler plate to use the APIs in Python and the ability to deploy custom analytics | Integrate custom analytics Leverage delair.ai computing resources | | |

| Analyze | | | | | |
|------------------------|---|---|---|--|--|
| | Proven r | eady-to-use applications for extra | cting business intelligence | | |
| Annotate | | Draw annotations, add descriptions and tag them to easily find them | Spatial elements: point, line, poli-line, polygon | | |
| Measure | | After drawing annotations, get instan- taneous measurements | Perimeter, surface area, volume, distance, elevation profile | | |
| | | OFF-THE-SHELF ANAL | YTICS | | |
| MINES & A. | Advanced stockpiles (M&A) | Automated inventory reporting toolset. View individual volumes, areas, and tonnage | Automated Stockpile identification and volume Stockpile location map, Stockpile inventory report Statistics dashboard | | |
| | Haul roads | Automatically extracts the most currently geometry and conditions of your haul roads | Haul road centerlines, Haul road widths, Haul road cross falls, Haul road grade | | |
| | Safety & higwalls | Automatically extracted safety analytics | Highwall heights, crests, toes – Safety block heights – Safety berm crest, toes and heights | | |
| | Advanced scouting maps | Get an overview of your field at the macro- field level | NDVI map - Crop vigor, MCARI2 map- Green biomass, NDRE map - Chlorophyll content, VARI map - Greenness, PRI map - Photochemical reflectance index, CCCI map - Chlorophyll concentration, CIR map - Colored infrared, MSAVI 2 map - Soil adjusted crop vigor | | |
| | Emergence characterisation | Automatically calculate the % of green/leafs to characterize vigor | Emergence layer, Emergence % per microplot | | |
| AGRICULTURE & FORESTRY | Field vectorisation | Automatically define geolocation of field boundaries and surfaces | Field boundaries | | |
| | Flowering characterisation | Automatically calculate the % of flowering | Emergence layer, Emergence % per microplot | | |
| | Fraction of vegetation cover | Automatically measure the fraction of ground covered by vegetation | Biomass mask, FCover per microplot | | |
| | Gaps and count | Automatically determines plant count and gaps | Gap length, Position of gap at line end or not, Plant count | | |
| | Microplot vectorisation | Automatically define geolocation of microplot boundaries | Microplots layer | | |
| | Plant height | Automatically estimate plant height | Vegetation height map | | |
| | Statistics plots | Automatically extracted statistics around scouting maps | Min, Max, Average, Standard deviation, Variance | | |
| | Stay green | Automatic assessment of crops remaining green late in the season | Stay green layer Stay greenper microplot | | |
| | Basic RGB classification | Classification of objects from a RGB dataset | 5 classes (Ground, Vegetation, Poles, Conductors, Custom class) | | |
| LITIES | Advanced LiDAR point classification | Classification of objects from a point cloud | 9 classes (Ground, Vegetation, Poles, Conductors, Buildings, Crossing Lines, Roads, Railways, Custom class) | | |
| | Thermal mapping | Orthomosaic generated from thermal LWIR pictures | Thermal orthophoto | | |
| & UT | Solar plant thermal inspection | Automatically detect hotspots on solar plants | Georeferenced map with anomalies | | |
| OWER | Basic LiDAR point cloud classification (P&U) | Classification of objects from a point cloud | 5 classes (Ground, Vegetation, Poles, Conductors, Custom class) | | |
| PO | Vectorized conductors | Automatically generate a 3D geo-referenced vector file of power lines catenaries | Vectorized conductors files | | |
| | Vegetation encroachment | Automatically detect vegetation surrounding powerlines | Text collision report, Map collision report, Collision detailed report, Falling tree report, Pruning report | | |
| CUSTOM ANALYTICS | | | | | |
| Object detection | | Automatically detect and classify different classes of objects from an RGB orthophoto | Tagged detected objects in 2D layers | | |



